Active/Active HA Job Scheduler and Resource Management

a proof-of-concept implementation

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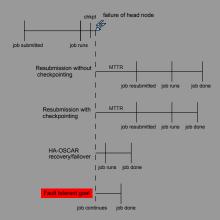
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- Research area of high availability for job scheduler
- Efforts focused on the head node
- Proposed solution uses the virtual synchrony paradigm
- Proof-of-concept application shows possible design solution

Project overview Project goals

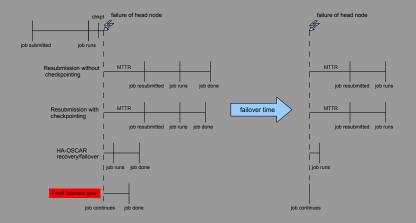


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Project overview Project goals



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Project overview Project goals

□ Job scheduler service providing Active/Active HA

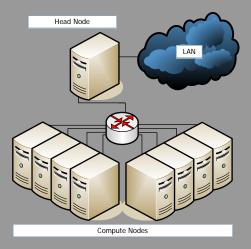
- No loss of scheduled job
- No loss of running job
- □ No restart of running jobs

Leading to uninterruptible service availability

- Seamless failover (actually none)
- Dynamic reconfiguration and recovery are completely masked
- □ High transparency of HA capabilities from the user

Cluster system architecture System concepts External components System design overview

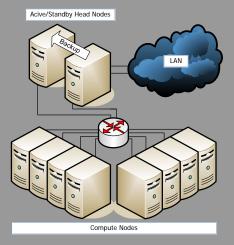
Beowulf cluster architecture



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HA-OSCAR cluster architecture

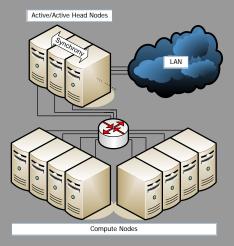


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Symmetric Active/Active HA cluster architecture



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Cluster system architecture System concepts External components System design overview

- Active state replication using virtual synchrony
- All messages are processed as uninterruptible events
- Global process state provided by external group communication system
- External replication used for resource and job management
- External components should be replaceable with new or similar ones
- Introduction of symmetric multi headed cluster architecture
- Any amount of head nodes possible \Rightarrow scalable high availability

Cluster system architecture System concepts External components System design overview



$$t_{down} = 8760 \cdot (1 - A)$$

 $A_{component} = \frac{MTBF}{MTBF+MTTR}$

 $A = 1 - (1 - A_{component})^n$

No. HN	Availability	Est. downtime
1 2 3 4 5	98,580441640%	5d 4h 21min

MTBF 5000 hours M

MTTR 72 hours

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1 2 3 4 5	98,580441640% 99,979848540%	5d 4h 21min 1h 45min

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3	99,999713938%	1min 30s
4	99,999995939%	1s
5	99,999999942%	18ms

MTBF 5000 hours

MTTR 72 hours

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Cluster system architecture System concepts External components System design overview

Group communication system transis

- Communication facilities for virtual synchrony
- □ Handles group membership changes

Resource management PBS TORQUE

- Enhanced version (>= version 2.0p1)
- Enabled multiserver architecture support

Job scheduler maui

Commonly used in conjunction with PBS

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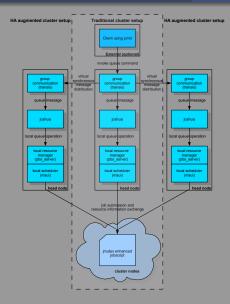
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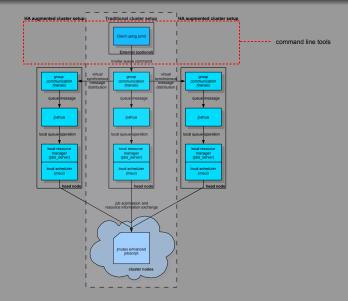
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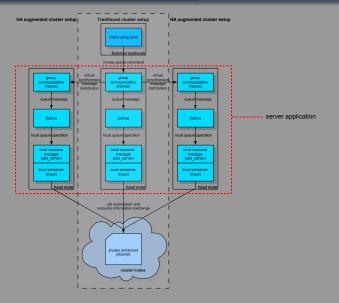
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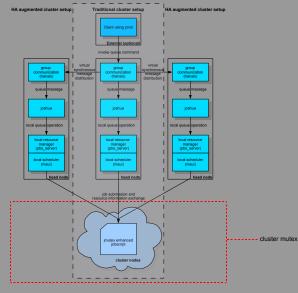
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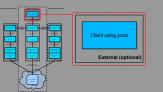


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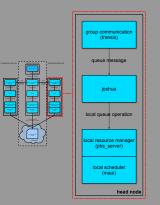
Command line tools



- □ Perform queue operation such as
 - Job submission
 - □ Job status information
 - □ Job removal from the queue
- Designed for high transparency to the user
- Enables simple replacement for former job queue commands
- Achieved by message encapsulation of argument vector, stdin and environment
- Effective command is redirected to the joshua server daemon

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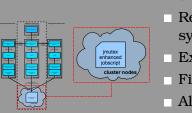
Server application



- Daemons act as transparent gateway for user commands
- Queue commands are received globally, executed locally
- Output is redirected to the client
- All joshua daemons run in virtual synchrony provided by transis
- Daemons form a group of head nodes
- Using group communication the group reconfigures itself in cases such as
 - Daemon joins
 - Daemon failure

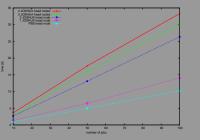
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Cluster mutex



- Distributed mutual exclusion across all cluster nodes
- Realized in connection with virtual synchrony
- Executor sends request for execution
- First gets the permission to run the job
- All other are put on hold
- When job is finished the pending executors will be released
- □ Solves the single instance problem

Results Future work Conclusion



- Reasonable cost for HA depends from number of head nodes
- Submission performance in linear scale
- Joshua handles parallel job submission, join and fail events as proposed
- Jmutex handles single instance execution problem
- Transis has some stability issues
- PSB is still focused on client-server model

Results Future work Conclusion

- □ Possible merge with HA-OSCAR project
- Integration and development of more reliable group communication system
- Use of more suitable external resource management system
- Add missing job manipulation features (hold, release)

- Take advantage of multi-headed architecture and the symmetric Active/Active HA design
- Prototype implementation could prove design to improve the cluster HA
- System availability is scalable as proposed
- Approach leads to a significant increase of availability of cluster head nodes
- First step toward non-stop computation by introducing a fault tolerant job scheduler

Results Future work Conclusion

Research Paper

K. Uhlemann, C. Engelmann and S. L. Scott. "JOSHUA: Active/Active high availability for HPC job and resource management". *To appear in proceedings of IEEE International Conference on Cluster Computing*, Barcelona September 25th-27th, 2006.